#### **VLTI Observing Preparation Sequence**

**EuroWinter School** 

**Observing with the Very Large Telescope Interferometer** 

Les Houches, France February 3-8, 2002

F. Malbet

#### LATE

Laboratoire d'Astrophysique de Grenoble 7 February 2002

## Outline

- I. Context of interferometric observations with the VLTI
  - ✓ VLT data flow system (DFS)
  - ✓ VLTI status
  - Phase 1 proposal preparation
- II. Observing preparation sequence:
  - ✓ Definition of astrophysical objectives
  - ✓ Estimation of technical feasibility
  - ✓ VLTI configuration
  - ✓ Instrument configuration
  - $\checkmark$  Calibration stars
  - $\checkmark$  Estimation of required time
  - $\checkmark$  Data reduction
- III. Practical working session

### VLT data flow system (DFS)



# VLT Data Flow System: Programme Handling (1)Usual proposal preparation (phase 1)

FS

- Scientific rationale
- Immediate objectives
- Instrument configuration
- Technical feasibility
- Estimation of required time

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Observing with the VLTI F. Malbet – VLTI Observing Preparation Sequence

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## VLT Data Flow System: Programme Handling (2)

#### **Preparation tools:**

- VLT user guide
- Instrument manual
- Exposure time calculator (provide SNR estimates)



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#### http://www.eso.org/observing/etc

#### ► OPC (Observing Programmes Committee) ranking: A, B, C

#### VLT Data Flow System: Observation Handling

#### Phase 2 Proposal Preparation (P2PP)

#### **Observation block (OB) = target information + instrument setup**

- OBs are the smallest schedulable unit of telescope resources
- OBs are quantum of data that flow within the DFS

Even in visitor mode, astronomers are requested to use OBs.

In **service mode**, OBs are stored in an **OB repository** from where a schedule can be constructed.

## VLT DFS: phase 2 proposal preparation (P2PP)

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### VLT Data Flow System: other steps

•Execution of Observing Blocks (OBs)

- Data archiving
- Data reduction pipeline
- •Quality control: quick-look tools & off-line analysis



## What about the VLTI?

Described in Ballester et al. (The ESO Messenger 106, 2, Dec 2001)

#### **Motivations:**

- High level of automation
- Service mode mandatory with interferometry
- Similar to VLT standard for maintenance

#### But there are some specifics:

- VLTI array configuration (telescopes, DL,...)
- Instrument configuration
- Valid observations require calibration stars

#### Not yet completely finalized

## VLTI Visibility calculator



Figure 1: The VLTI Visibility Calculator (preliminary design). The VLTI Visibility Calculator will be an Internet application similar to the ESO Exposure Time Calculators. The prototype is using the ASPROI JMMC software as a calculation engine.

## Objective of the tutorial / work session



## Example of preparation sequence with AMBER



## Scientific objectives

Not images, but **complex visibilities** : think in Fourier space (cf. PWS-1)



#### **Observables:**

- Visibility amplitudes: AMBER & MIDI (cf. Berger, seminars, PWS-1,2)
- *Differential phases*: AMBER & MIDI (cf. Stee)
- Closure phases: AMBER (cf. Buscher, Monnier)

## Immediate objectives

#### What do you want to do?

- Wavelength: AMBER or MIDI
- Number of targets: few ones or survey
- Magnitude of the objects: AT/UT, fringe tracking, spectral resolution
- Type of object structure:
  - simple (binary, photosphere, ...)  $\rightarrow$  visibility amplitudes
  - asymmetry  $\rightarrow$  closure phases
  - high contrast  $\rightarrow$  high accuracy
  - Spectral signature  $\rightarrow$  differential phases
  - Type of (*u*, *v*) coverage: few points, (*u*, *v*) tracks, full (*u*, *v*) coverage

#### In short, what are you going to demonstrate...

## An example...

Detection of the binary Z Canis Majoris at 10 microns.

- separation 0.1",
- PA 120 degrees,
- flux ratio, 10%?
- detect the flux ratio in order to separate the contribution between the 2 components and eventually detect the accretion disk...

## Observability

Object magnitudes are within instrument sensibility
Reference objects for tracking: self-reference or off-axis
Position in the sky → observing time slots

A vailable data: Basic data, Identifiers Plot & image tools Bibliography Measurement	nts <u>External archives</u>
Basic data: HD 53179 T Tau-type Star	Query around with radius 10 arc min
ICRS 2000.0 coordinates <b>07 0</b> <u>1997</u>	3 43.1619 -11 33 06.209 [27.65 16.15 71] A A&A323L49P
FK5 2000.0/2000.0 coordinates <b>07 0</b> 3	3 43.16 -11 33 06.2 [27.65 16.15 71]
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Galactic coordinates 224.	61 -2.56 V magnitude (AO)
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Spectral type <b>Bpe</b>	
Radial velocity (v:Km/s) or Redshift (z) v +2	8 [ 20] E <u>1979IAUS3057E</u>
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## **VLTI** configuration

- •Hardware: 2 or 3 telescopes, ATs or UTs, AO and FT or not,....
- •Baseline strategies:
  - short, intermediate or long ones
  - Earth synthesis: North-South, East-West or mixed?



## MIDI/AMBER configuration

cf. AMBER and MIDI presentation



#### External references / calibration stars

We need stars of about the same brightness, but no tools exist yet for 10 microns calibrators...

#### • 🗆 🗙 🗙 🗝 getCal Return -- Z CMa /home/user/getCal/getCal-2.4/getCal -targetName Z CMa -lClass V ### GUI catalog from getCal v2.4pre3 ### # Resolving target Z CMa via SIMBAD # target HD 53179 # HIP 34042 (HD 53179) has his multiple component flag set to V # Warning: the V designation indicates suspected variability-induced movement HDC53179 07 03 43.162 -11 33 06.209 -0.009 0.003 9.8 9.8 Bpe 0.0 xxx xxx trg # HIP 30867 (HD 45725) has his variability flag set (2) # with 0.022 mag scatter in 159 observations # HIP 30867 (HD 45725) has his multiple component flag set to C the C designation indicates solutions were found for individual components 3 components: # A component -- V= 4.630 B component -- V= 4.996 at sep 7.161 arcsec/PA 133 deg C component -- V= 5.385 at sep 9.91 arcsec/PA 125 deg HDC45725 06 28 49.070 -07 01 59.025 -0.007 -0.005 3.8 4.3 B3Ve 9.7 0.29+/-0.1 cal HDC5317 HDC46304 06 32 23.129 -05 52 07.752 -0.001 -0.042 5.6 4.9 FOVnn+... 9.6 0.36+/-0.1 cal HD HDC50281 06 52 18.050 -05 10 25.367 -0.547 -0.003 6.6 4.2 K3V 7.0 0.77+/-0.1 cal HDC53179 HDC58461 07 25 08.315 -13 45 07.120 -0.209 -0.001 5.8 4.9 F3V 5.7 0.39+/-0.1 cal HDC53179 # HIP 36186 (HD 58954) has his variability flag set (1) # with 0.017 mag scatter in 110 observations # HIP 36186 (HD 58954) has his multiple component flag set to C the C designation indicates solutions were found for individual components

## Exposure time calculator

CO ORODT		
HDUK1		
Calculate th	e accuracy with which the model parameters could be estimated	
UV Table Name	modelž	
umber of Functions (1 or 2)	1	
Function 1:	BINARY	Choices
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Function 2:	POINT	Choices
Par <mark>http</mark> Masked parameters (0 or 1)	o://www.eso.org/observing/etc	
unction 1 arameter 1: Masked arameter 2: Masked arameter 3: Stdev = arameter 4: Stdev = arameter 5: Stdev = arameter 6: Stdev =	1.12188974E-05 4.939123E-05 2.73385492E-07 2.66978205E-07 completion	

## Technical and astrophysical feasability

#### In case of the example

- require at least a full transit, maybe two nights
- bright source and the accuracy depends on the source contrast

- Interpretation plan:
  - SED complete up to 10 microns for the two stars
  - Detection of a possible accretion disk: disk models

#### Summary: sequence of the preparation

1. scientific rationale

2. immediate objectives

3. list of the targets with the appropriate magnitudes (JHK for AMBER, N for MIDI) but also the V magnitude and spectral type for active guiding

4. requested VLTI configuration:

a. Telescopes: UT/AT

b. Baseline(s)

c. Hour angle range

d. Schedule constrains: dark moon, part of the night

e. Fringe tracker, dual-feed

5. requested instrument configuration (cf. instrument presentations):

a. spectral configuration

b. other parameters

c. required accuracy (visibility or phase)

6. calibrators: strategy, list of calibrator stars

7. technical feasibility:

a. expected visibility range

b. date of observations

c. total observing time

8. preparation tasks if any

9. plan for interpreting the data

10. general conclusion on the exercize

## Conclusion

- The ESO data flow system allows to concentrate on Phase 1 and Phase 2 proposal preparation

- Service mode mainly
- Observing Blocks are the smallest schedulable quantity
- Data reduction pipeline

The sequence of preparation is almost always the same:

Use of a program to:

- configure the array,
- compute the SNR,
- test some ideas (with ad-hoc or homemade models),
- find calibrators